

## Homework 2 (Chapters 1 & 2)

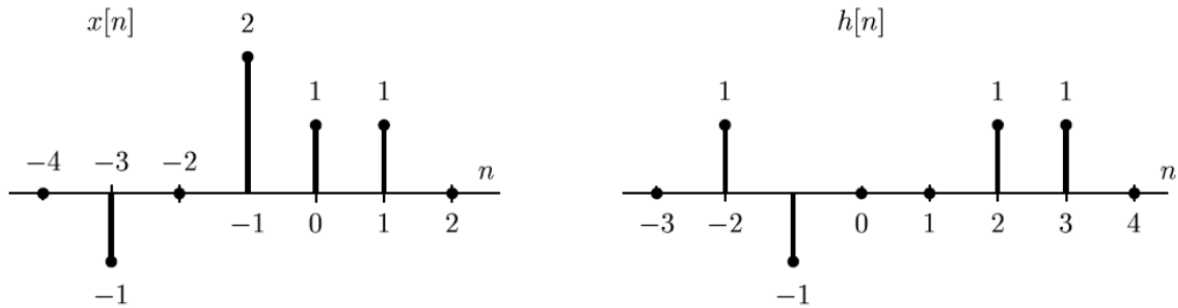
### Problems:

1. Consider the signal

$$x(t) = u(t) - u(t-1) + (4-2t)[u(t-1) - u(t-2)]$$

- a. Sketch the signal  $x(t)$ .
  - b. Sketch the odd part of  $x(t)$ .
  - c. Sketch the signal  $y(t) = 2x(3 - \frac{t}{2})$ .
  - d. Sketch the signal  $g(t) = \frac{d}{dt}x(t)$ .
2. Determine whether each of the following signals is periodic. If the signal is periodic, state its period and fundamental frequency.
- a.  $[\sin(\pi n/5)]/(\pi n)$
  - b.  $e^{j(2\pi n/8)}$
  - c.  $e^{jn}$
3. For each of following systems determine whether the system is stable, causal, linear, time invariant and memory less:
- a.  $y[n] = x[-|n|]^2$
  - b.  $y[n] = x[n] + x[n-1]$
  - c.  $y[n] = (-0.5)^2(x[n]+1)$
  - d.  $y[n] = x[n^2]$
  - e.  $y[n] = (\cos(\pi n)).x[n]$
  - f.  $y[n] = \sum_{k=n-1}^{\infty} x[k]$
  - g.  $y(t) = e^{-|x(t)|} \cdot \log(x(t) + 1)$
  - h.  $y(t) = x(\frac{t}{2}) \cdot \cos(x^2(t))$
4. Consider a system with input  $x[n]$  and output  $y[n]$ . The input-output relationship is defined by the following two properties:
- a.  $y[n] + \alpha y[n-1] = x[n]$ ,
  - b.  $y[0] = 1$ .
- a. Determine whether the system is time invariant.
  - b. Determine whether the system is linear.
  - c. Assume that the difference equation (property 1) remains the same, but the value  $y[0]$  is specified to be zero. Does this change your answer to either Part (a) or Part (b)?

5. Compute the convolution sum  $y[n] = x[n]*h[n]$  for each of the following pairs of signals.



- a.  $x[n] = u[n+4] - u[n-1]$  ,  $h[n] = 2^n \cdot u[2-n]$   
 b.  $x[n]$  and  $h[n]$  are depicted above.

6. Prove that if a system is linear and causal, then is in initial rest condition (i.e. if  $x[n] = 0$  for  $n < n_0$ , then  $y[n] = 0$  for  $n < n_0$ ).
7. The followings are the impulse responses of LTI systems. Determine whether each system is causal and/or stable. Justify your answers.
- $h[n] = 2^n \cdot u[3-n]$
  - $[1 - 0.99^n] \cdot u[n]$
  - $2u[n+5] - u[n] - u[n-5]$
  - $h(t) = u(1-t) - (1/2)e^{-t}u(t)$
  - $h(t) = e^{15t}[u(t-1) - u(t-100)]$
8. Consider an LTI system whose response to the signal  $x_1(t)$  is the signal  $y_1(t)$  where these signals are defined below. Determine and provide a labeled sketch of the response to the input  $x_2(t)$ , which is also defined below.

$$x_1(t) = u(t+1) - u(t-1),$$

$$y_1(t) = \begin{cases} t + 2, & -2 < t < 0 \\ -t + 2, & 0 < t < 2 \end{cases}$$

$$y_2(t) = \begin{cases} t + 2 & -2 < t < -1 \\ 1 & -1 < t < 1 \\ -t + 2 & 1 < t < 2 \end{cases}$$

9. The input  $x(t)$  to a system yields the output  $y(t)$ , as shown below. Sketch the response  $y(t)$  when the input is  $x(t) = u(t+1) - u(t-2)$ .

